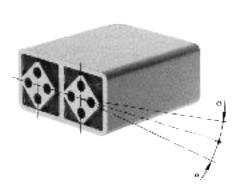
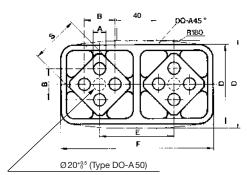
# **ROSTA**

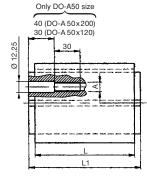


# **Rubber Suspension Unit (as Elastic Drive Head)**

# Type DO-A







Art. No.	Туре	cq	L	L1-0.3	А	В	D	E	F	S	Weight in kg
01 041 008	DO-A 27 x 60	160	60	65	8 + 0.5	20 ±0.4	47 <sup>±0.15</sup>	44	91 +0.2	27	0.47
01 041 011	DO-A 38 x 80	210	80	90	10 + 0.5	25 <sup>±0.4</sup>	63 <sup>±0.2</sup>	60	123 +0.3	38	1.15
01 041 013	DO-A 45 x 80	220	80	90	12+0.5	35 <sup>±0.5</sup>	85	73	149.4 +1.6	45	1.85
01 041 014	DO-A 45 x 100	260	100	110	12 + 0.5	35 <sup>±0.5</sup>	85	73	149.4 +1.6	45	2.26
01 041 016	DO-A 50 x 120	400	120	130	M12	40 ±0.5	89	78	167	50	5.50
01 041 017	DO-A 50 x 200	600	200	210	M12	40 <sup>±0.5</sup>	89	78	167	50	8.50

 $c_d$  = dynamic spring value N/mm at  $4 \pm 5^\circ$ , in frequency range  $300 - 600 \text{ min}^{-1}$  Elements with heigher load capacity are available on request.

#### **Material Structure**

The housings up to size DO-A 45 are made out of light alloy profiles, housing of size 50 in nodular cast; inner squares in light alloy profile with 4 bores for the fixation of connection brackets shaker: eccentric rod.

## **Typical Calculation**

ROSTA rubber suspension units DO-A employed as elastic drive heads are to be selected so that their spring value corresponds roughly to the total spring value. The oscillation angle  $\alpha$  of the units must not exceed  $\pm$  5°. Elastic drive heads shall only be used in combination with **resonance** shaker conveyors.

#### Given:

Total weight of oscillating mass m = 210 kgSpeed  $n_{err}$  =  $320 \text{ min}^{-1}$ Eccentric radius R = 14 mm

#### Wanted:

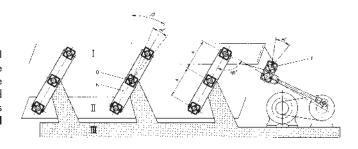
Total spring c<sub>t</sub> in N/mm

 $c_{t} = m \cdot \left(\frac{2\pi}{60} \cdot n_{err}\right)^{2} \cdot 0.001 = 210 \cdot \left(\frac{2\pi}{60} \cdot 320\right)^{2} \cdot 0.001 = 235.8 \; N/mm$ 

**Selected:** 1 piece of DO-A 45 x 100

## **Guidelines for Fitting**

The elastic slider crank drive may be applied optionally onto the trough I or the contermass II, at the beginning of the trough or elsewhere. Force introduction must be 90° to the angle  $\beta$  of the rocker suspensions. The unit axis must be 90° to the longitudinal axis of the conveyor trough and run centrally with this. Fixing is by shaft screws of 8.8 quality (analogous to fixing the universal joint support). **Elastic drive heads should only be applied in natural frequency shaker systems!** 



<sup>\*</sup> DO-A 45 with convex housing shape